Future Combat Systems

11th Annual US Army Ground Vehicle Survivability Symposium March 28, 2000



Marion H. Van Fosson, LTC, USA PM Future Combat Systems mvanfosson@darpa.mil

Agreements Officer	Ms. Swatloski	rswatloski@darpa.mil
TRADOC	COL Page	paget@monroe.army.mil
DPM	Mr. Marrero	marrerop@tacom.army.mil
DCSOPS	MAJ Brown	Tyrone.Brown@HQDA.Army.Mil
SETA	Steve Scharf	sscharf@sysplan.com



Agenda

- The Problem
- The Challenge
- Technical Approach
- System Technology Options
- FCS Survivability
- Summary



CSA Statement of the Problem

GVSS328-2

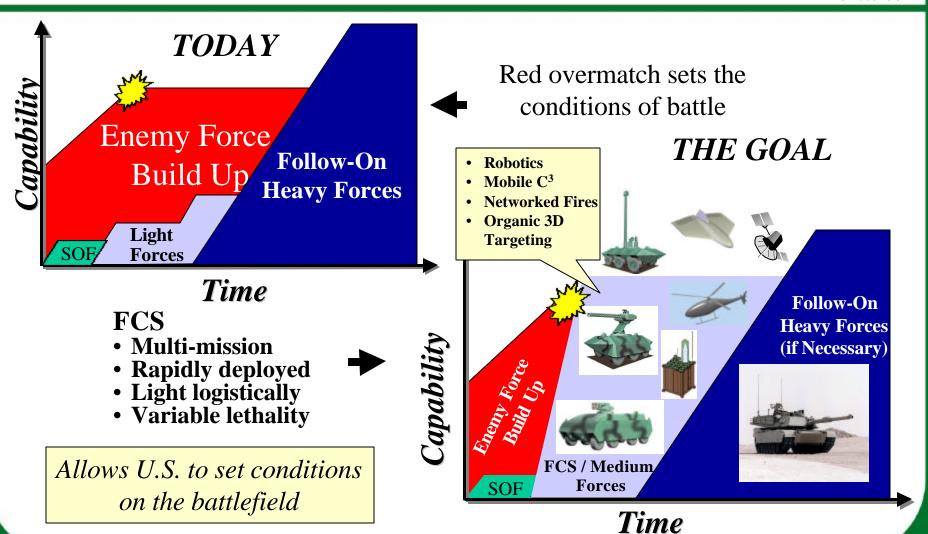


"We must provide early entry forces that can operate jointly, without access to fixed forward bases, but we still need the power to slug it out and win decisively. Today, our heavy forces are too heavy and our light forces lack staying power. We will address those mismatches." -- GEN Shinseki, CSA, 23 June 1999



The Challenge:

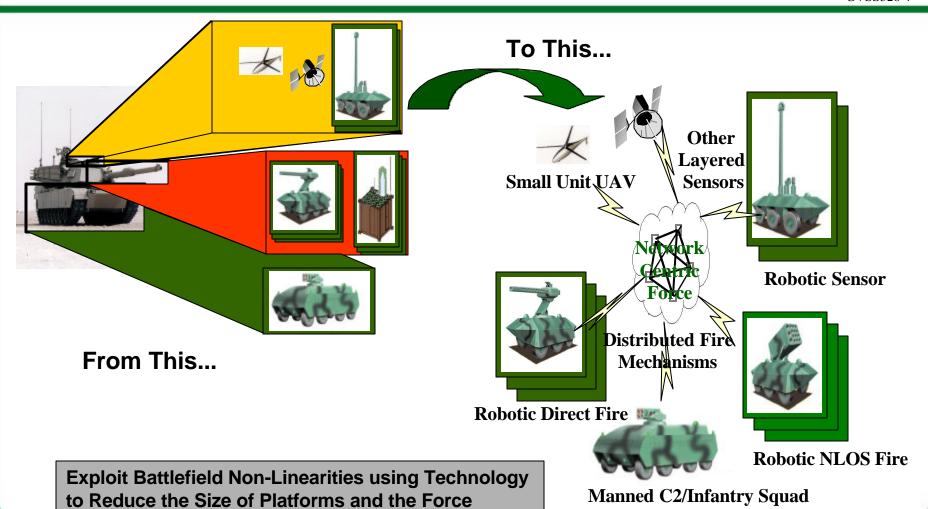
Lethal, Effective Early Entry Forces



Approved for Public Release, Distribution Unlimited



Technical Approach Network Centric Distributed Platforms

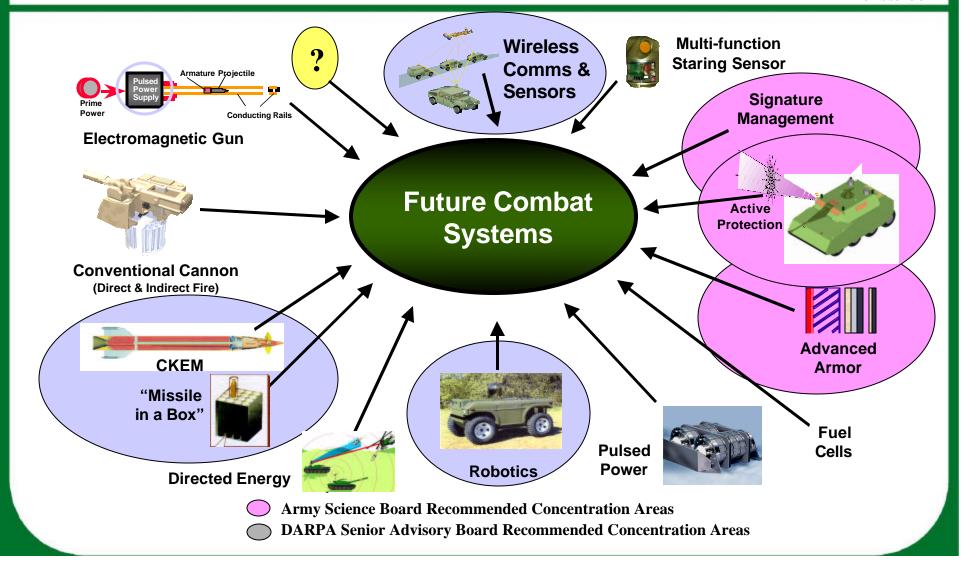


Approved for Public Release, Distribution Unlimited



System Technology Options

Future Combat Systems Draw From the Fullest Range of Technology Options





FCS Survivability Baseline

GVSS328-6



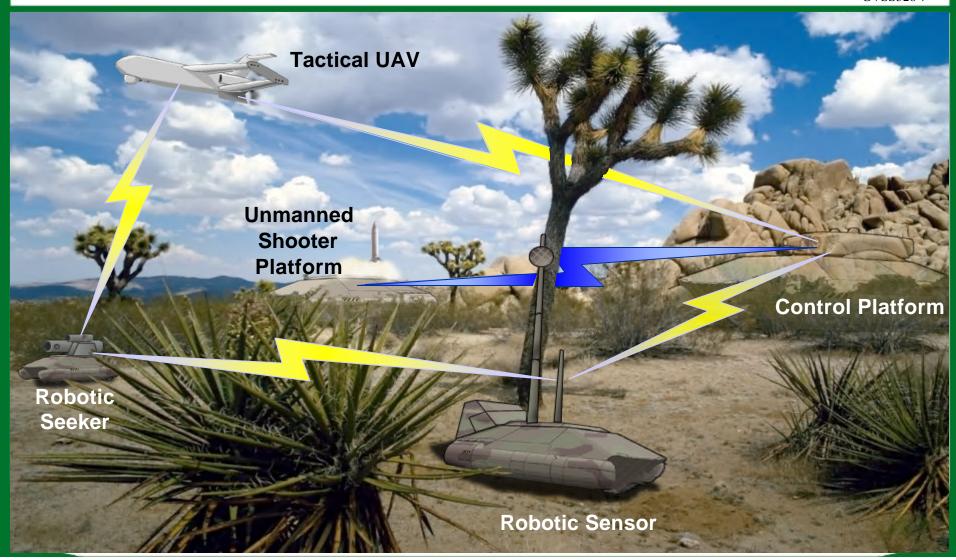
• FCS Concept Survivability

- Smaller functional platforms
 - Harder to see
 - Harder to be targeted
 - Enhanced signature management
- Distribution of mission functions between platforms
 - Enhanced mission survivability
 - Maximize advantages of terrain features
- Networked assets
 - Task sharing and mutual protection
 - Remote threat engagement
- Enhanced situational awareness
 - Inter-platform mutual protection
- Application of unmanned systems
 - Remove the soldier from harms way



Future Combat Systems

Enhanced Survivability Through Shared Functions & Networking





FCS Survivability

Don't be Detected

GVSS328-8



Typical Enabling Technologies

- Advanced materials
- Advanced communications and sensors
- Digitization
- Hybrid power and energy

Sample Supporting Programs

- Small Unit Operations (SUO)
- Combat Hybrid Power Systems (CHPS)

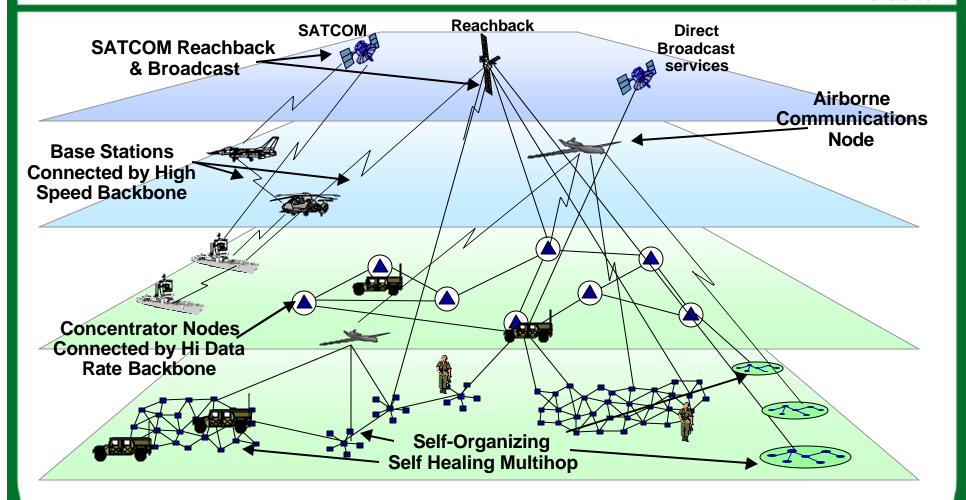
- Network survivability
- Platform design and packaging
- Enhanced situational awareness
- Maximum implementation of effective passive solutions
- Electromagnetic and thermal signature management

Approved for Public Release, Distribution Unlimited



Vision: A Survivable, Mobile, Adaptive, Ad Hoc Tactical Network

GVSS328-9



SUO SAS and GloMo Programs Provide the Foundation



Combat Hybrid Power Systems (CHPS)

Supports platform size reduction and silent operations

GVSS328-10





Energy /Power Storage Li-Ion Battery/Flywheel

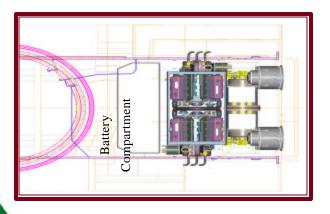


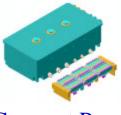
IMPROVED SIL



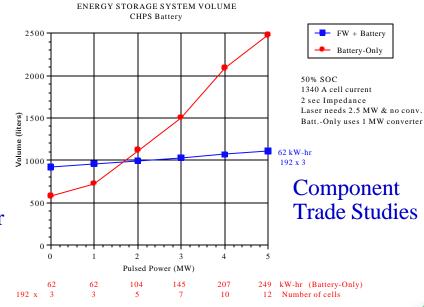
High Power Density Prime Mover

Evaluation of system architectures using real hardware & validated models





Compact Power Conversion -SiC & hiT Si





FCS Survivability

Don't be Hit

GVSS328-11



Typical Enabling Technologies

- Signal jamming
- Decoys and deception
- Active protection
- Advanced sensors

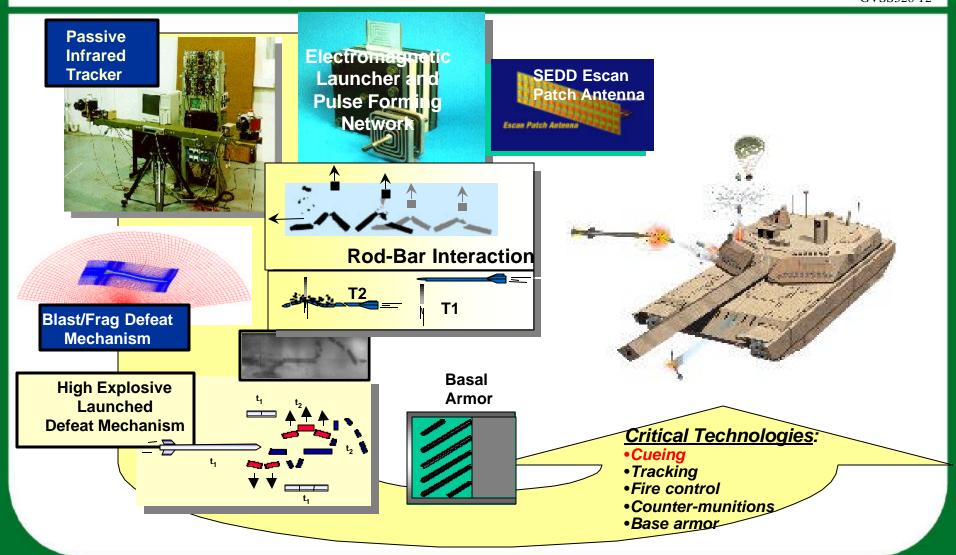
Sample Supporting Programs

Army Active Protection Systems (APS)

- Threat detection
- Response Time
- Threat neutralization alternatives and tactics
- Minimizing collateral damage
- Signature management
- Network "Cooperative Engagement"



Kinetic Energy Active Protection





FCS Survivability

Don't be Penetrated

GVSS328-13



• Typical Enabling Technologies

- Advanced passive materials
- Advanced energetic materials
- Electromagnetics

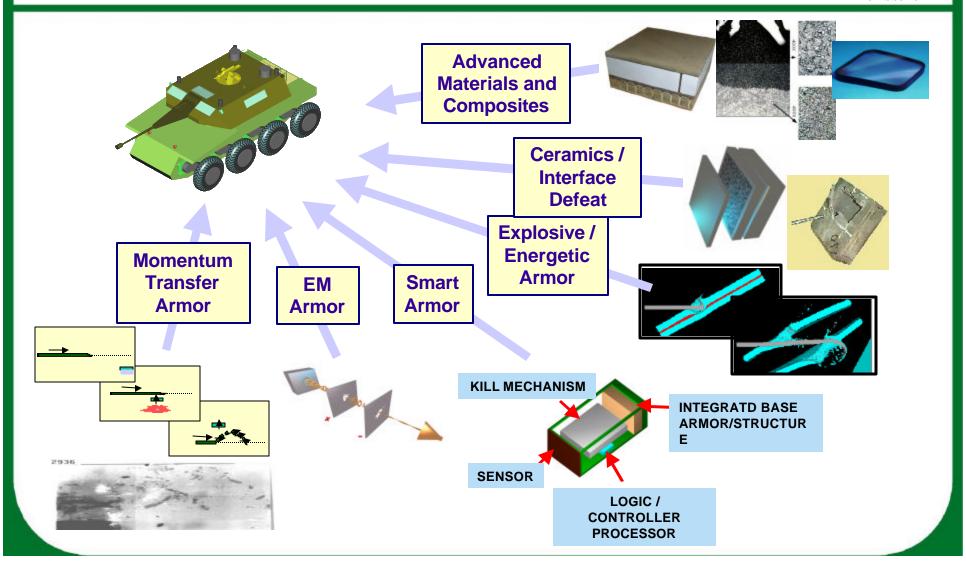
Sample Supporting Programs

- Army lightweight passive armor programs
- Army integrated armor/structure programs

- Defining threat boundary for armor protection
- Addressing solutions for growth potential
- Network survivability
- Minimizing collateral damage
- Electromagnetic signature management

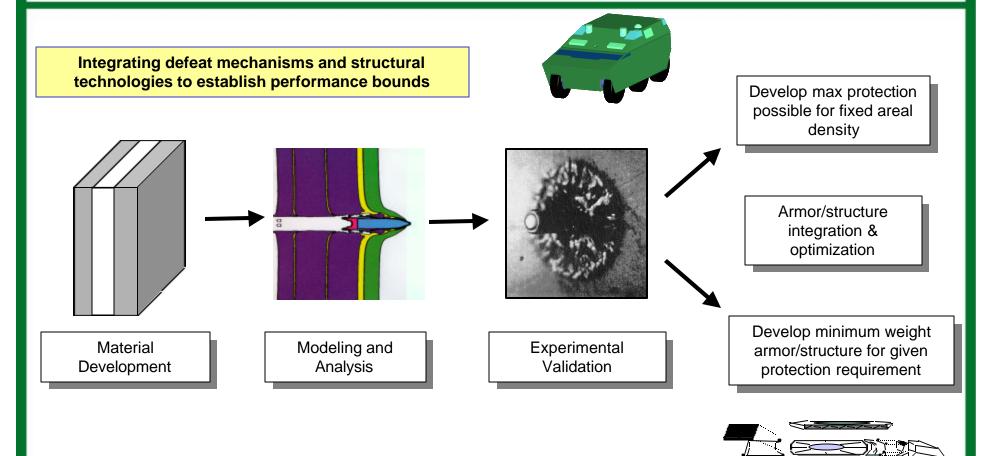


Lightweight Passive Armor





Integrated Armor/Structure Systems for Light Weight Vehicles





FCS Survivability

Don't be Killed

GVSS328-16



• Typical Enabling Technologies

- Robotics/Autonomy
- High energy absorption materials
- Internal platform design/fire suppression
- Spall suppression

Sample Supporting Programs

- Demo III
- Joint Robotics Program

- Internal platform design optimization
- Providing effective spall protection
- Effective blast and fire protection
- Prevention of 2nd round hit
- Mission continuation with remaining system assets

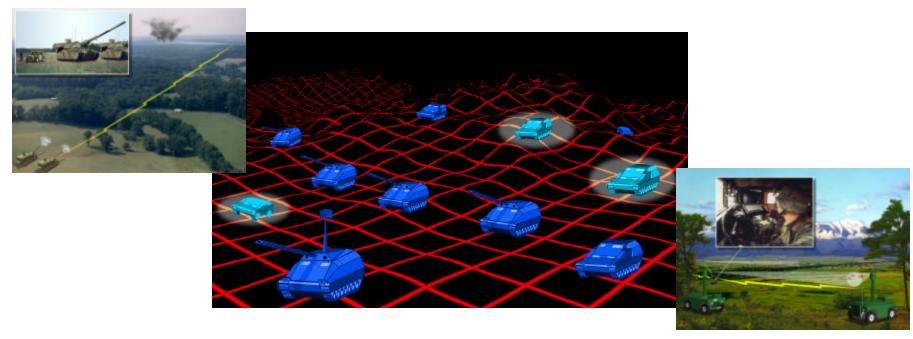
Approved for Public Release, Distribution Unlimited



A Vision of Future Land Combat

Robotics Technology Contributing to Manned & Unmanned Systems

GVSS328-17



Mobile robotic systems and robotics technology in the air and on the ground, are essential: for situational awareness, for fire support, for logistics, for communications, and as aids to reduce the severe physical and mental overburden of future combat



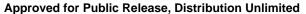
DOJ

Contingency support

DOD Interagency Collaboration in Robotics

GVSS328-18

Technical Focus Agency **FY90 FY92 FY94 FY96 FY98** DOC Real time sensory interactive control Computing architecture Retrotraverse navigation Architecture standards Standardized vehicle actuation Demo I NASA Stereo machine vision Obstacle detection Mustang Demo III Active gaze control CMU planner integrationTerrain classification Terrain adaptive velocity Demo II Low data rate video Demo I DOE compression for mobility Advanced manipulator Tactical unmanned vehicle prototypes Tasking & Control SARGE **TMR** Baseline advanced highway TMAP - Late 80's DOT system experimentationAutonomous road following





FCS Survivability -

An Added Dimension

Don't be There!

GVSS328-19



Typical Enabling Technologies

- Tagging
- Advanced UAV's
- Remote Fires

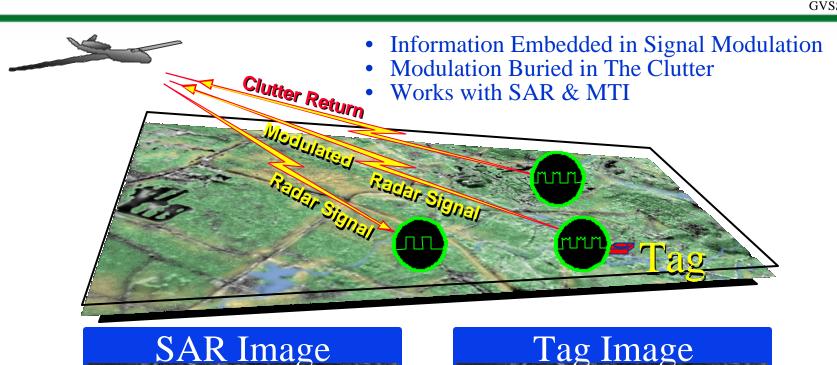
Sample Supporting Programs

- RF Tags
- A-160
- Advanced Fire Support System(AFSS)

- Identify and track targets
- Provide robust and secure communications and networks to empower decision options
- Overcome time latency problems
- Identify action protocols and rules of engagement



Digital RF Tags Program System Concept









A160 Unmanned Helicopter System Concept

GVSS328-21



Advanced Rotorcraft Technology

- Low Disk Loading for Efficient Low Power Loiter
- Low Rotor Tip Speed
- Hingeless, "Rigid" Rotor

Unmanned Helicopter for Surveillance, Ground Support

- > 30-48 Hours Endurance
- > EO/IR Search/Designator and SAR/MTI Radar Payloads
- > Reduced acoustic signature
- Significant Increase in Hover and Cruise Altitude
- Supply of Land and Sea Forces
 - > 500-1000 nautical mile Range with Cargo Payload
- Deployable to long ranges from Land and Ship Bases
 - > 2000-3000 nautical mile Range with Surveillance Payload



Advanced Fire Support System

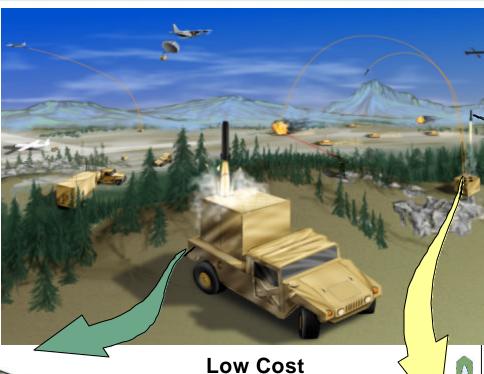
GVSS328-22

New Military Capability

- Immediate firepower
- 5x-10x kills per ton vs current ordnance
- Large zone of influence
- Multimode seekers
- In-flight targeting
- Duration weapon

Designed for Deployability

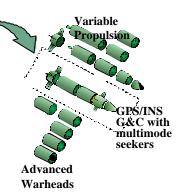
- Logistic efficiency through containerization
- No platform or crew required



- Reduced personnel and vehicles
 - LCC reduced > 50%
- CAIV design process
- Commonality of components and assembly

Family of **Missiles**

• Modular design



Modular Vertical Launch

- Self locating / orienting
- Unmanned operation
- Not platform specific
- Can be vehicle appliqué



Summary

- FCS survivability demands a balanced solution
- Distributed systems are more survivable and harder to detect
- Distributed systems enhance the survivability of manned platforms
- Electromagnetic and thermal signatures must be reduced
- Survivability of Networks will be as important as the survivability of our guns and weapons platforms